

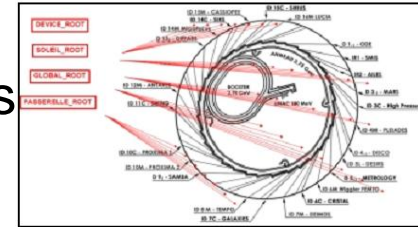


# Good practices for Tango DeviceServers development

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On behalf the Tango team*

# SOLEIL and Tango

- ❑ SOLEIL started a collaboration with ESRF on TANGO in 2002
- ❑ Nowadays, SOLEIL operates 30 Tango Control Systems
  - ➡ 1 for accelerators
  - ➡ 1 for each beamline



- ❑ The ICA team (about 20 people) is in charge of the development, maintenance and operation of software for Controls and Data Acquisition
  - ➡ Software engineering skills
  - ➡ From Tango controls
  - ➡ Up to GUI (See COMETE framework presentation on Friday)
  - ➡ Data management at the application levels (for data storage and data retrieval)



Writing a Tango Server  
is easy.  
So what ?

# Developing a DeviceServer in 5 minutes

- ❑ Use POGO to generate the code skeleton
- ❑ Implement the relevant methods to read/write attributes
- ❑ Implement the relevant methods to execute commands
- ❑ Compile and link with Tango libraries
- ❑ Declare the DeviceServers and its associated devices within jive
- ❑ Start the binary
- ❑ Run you client application (for instance ATKPanel)
- ❑ That's fine you can remotely control your equipement

**It is easy !! No ?**

# That's how we started in 2002 at SOLEIL

- ❑ We had to develop a Control system for our Accelerators and for 30 beamlines and no single line of code to do it
- ❑ We started developing our first Tango DeviceServers with the previous method
  - ☞ Because we had to learn how to do it properly
  - ☞ We were “regular” “young” “software developers” : (N.I.H syndrom, God vision when developing code, etc..)
  - ☞ Because we had a lot of pressure from our users to be able to control their equipments
- ❑ But we already knew this method is not sufficient when you plan to :
  - ☞ Use Tango devices as a “LEGO” bricks that will have to be reused and recomposed in various contexts
  - ☞ Maintain the code for 30 years
  - ☞ Obtain very high rates of software reliability (which is mandatory if you plan to deliver 6000 hours of beam per year)
  - ☞ Be able to automate user processes in a reliable and reproducible manner

# Why using Guidelines for design and implementation ?

# Then software engineering practices are mandatory to achieve such results

- ❑ At SOLEIL we developed about 400 different Tango DeviceServer
  - ☞ Interfacing all kind of equipment's (power supply , motion systems, beam diagnostics, etc.)
  - ☞ Interfacing “pure software” devices (such as Scanning engine, Calculation routines, etc..)
- ❑ This development work has been done by more than 10 different developers
  - ☞ with different skills and knowledge on Java and C++ programming
- ❑ We also had an operational feedback on what we did
  - ☞ Being in daily contact with Machine and Beamline users
  - ☞ Doing also “On call” duties 6000 hours per year
- ❑ We accumulated an important “in house experience” of developing “Good” TangoDeviceServer
- ❑ In 2012 we had the opportunity thanks to our collaboration with MAX-IV to hire external experienced software engineers to summarise this experience in a document for the Tango Community



# Tango Guidelines



Version 1.4

## TANGO DeviceServers Design & Implementation Guidelines

### Diffusion :

*Distribution list : Tango mailing list*

*Copy to :*

Date	Writer	Reviewer	Approver	Modifications	Version
19/06/2012	S.GARA S. MINOLLI	N.LECLERCQ A.BUTEAU			0
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16/11/2012	JM CHAIZE E.TAUREL	A.BUTEAU		Remarks following SOLEIL/ESRF meeting	3



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# Standardizing design and coding practices is a win-win approach

## □ At the community level:

- ☞ To be able to reuse « good quality » DeviceServers developed by other institutes
  - ✓ Avoiding the cost of « redoing » everything on our own
- ☞ To ease Tango usage for newcomers
  - ✓ Which helps enlarging then the community

## □ At the institute level

- ☞ To be able to easily integrate new software developers resources
- The « Tango design guidelines » is quite a dense document which you must take time to understand and read carefully

# Overview of the “Tango DeviceServers design and implementation Guidelines”

# Tango concepts revisited

# Device : Concept

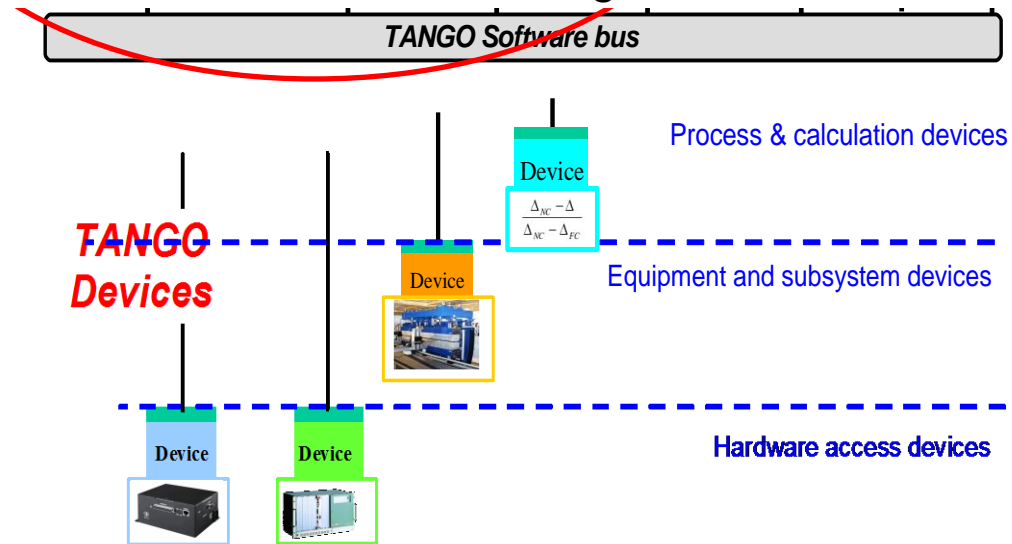
- ❑ Historically a device is an entity to control (Hardware or software )
- ❑ device = 1 polymorphous object
  - ➡ 1 equipement (ex: 1 power supply)
  - ➡ 1 collection of equipment (ex: 1 motor + 1 coder)
- ❑ A pure software component e.g :
  - ➡ A scan device
  - ➡ A data fitter device

## ***Recommandations :***

- ***A Tango device allows to make an abstraction of the equipment nature and implementation details***
- ***1 Device = 1 service = 1 element of the system***

# Device : Hierarchy

- A Tango control system can be logically hierarchically organized
  - ☞ At higher level the devices are logical to :
    - ✓ Manage and represent subsets of the control system
    - ✓ To perform sequences of actions on low level devices
  - ☞ These higher level of device must evolve regardless of real hardware

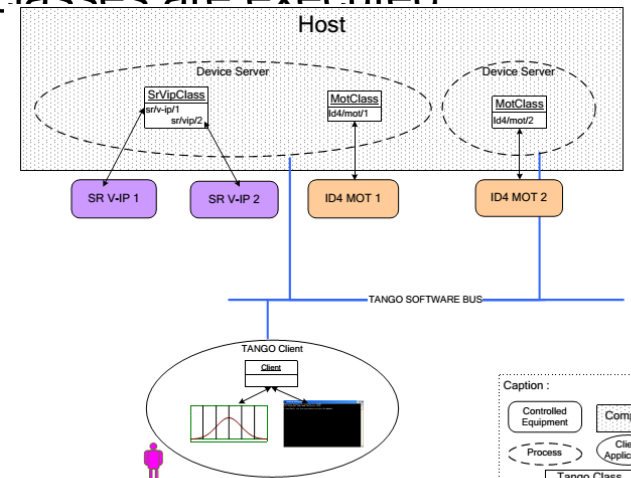


**Recommendation : Design your Tango Control system with a hierarchical view in mind (even if technically Tango doesn't impose this structure)**

# Vocabulary misunderstandings

- ❑ Sometimes, there are misuses of language regarding the concepts of: device, device server and TANGO class.
- ❑ TANGO class:
  - ☞ a class defining the interface and implementing the device control or the implementation of a software treatment.
- ❑ Device:
  - ☞ An instance of a TANGO class giving access to the services of the class.
- ❑ Device Server:
  - ☞ A process in which one or more TANGO classes are executed

**Recommendation : These three concepts are closely related, but they express different and important concepts of Tango. Take time to clearly understand them!**



# Attributes and commands

- Attribute : Definition
  - Physical unit produced or administrated by the device
    - ex: motor position, power emitted by a power supply, ...
  - **The main purpose of an attribute is to replace getters and setters.**
- Command: Definition
  - **A command is associated with an action. *On, Off, Start, Stop* are commons examples**

***Recommandation : To get an information produced by a device prefer Attributes (that can be archived or monitored in trends ) than Commands***



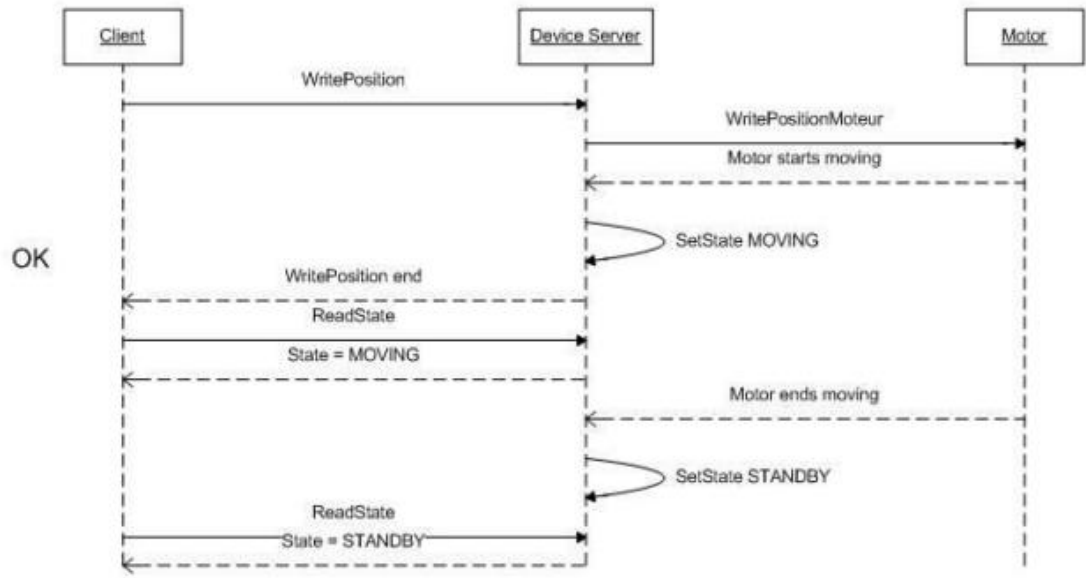
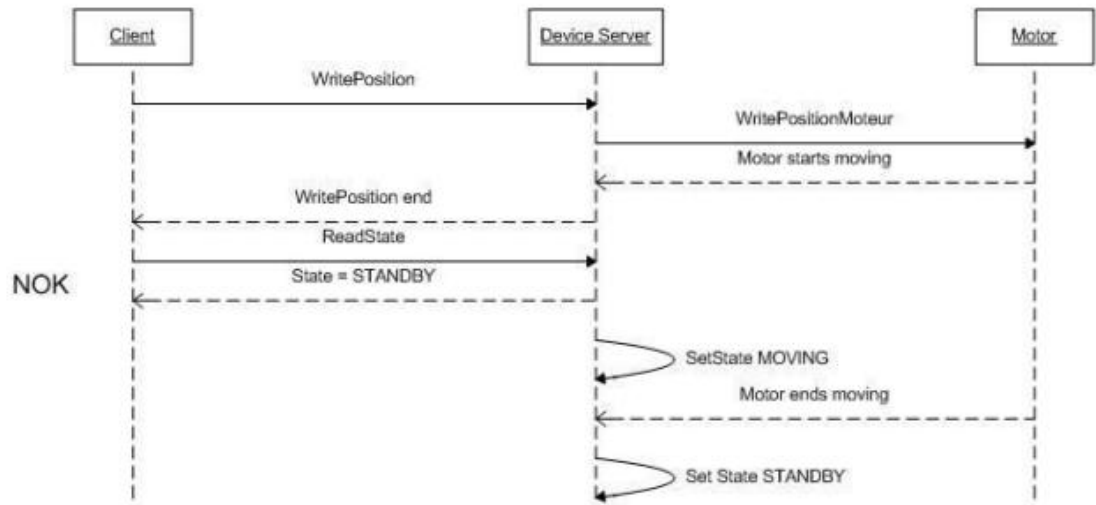
# States

- A TANGO device has a UNIQUE state (meaning a finite state machine).
- The device state is a key element in its integration into the control system.
- Therefore, you should be very careful in the management of state transitions in the device implementation

## ***Recommendations :***

- ***The device state must, at any time, reflect the internal state of the system it represents.***
- ***The state should represent any change made by a client's request.***
- ***Use always the same set of states for similar conditions .At SOLEIL:***
  - ***all Actuators are MOVING (when moving)***
  - ***all Sensors are "RUNNING" (when acquiring data)***
- ***Be careful to "non desired" transient state that will raise problem on higher level***

# State



# Design recommendations

# Reusability

- Estimates systematically, before coding a device, the possibility of reusing a device available in the code repositories
- Design the device as reusable/extensible as possible because it may interest the others developers in the community.

## *Recommandations :*

- *Configurable: (e.g.: no port number “hard coded”, but use of a parameter via a property)*
- *Self-supporting: the device must be usable outside the private programming environment (eg: all the necessary elements to use the device (compile, link) must be provided to the community).*
- *The use of the GPL should be considered, and the use of proprietary libraries should be avoided if possible*
- *Portable: the device code must be (as much as possible) independent of the target platform unless it depends on platform specific drivers*
- *Documented in English*

# Generic interface programming

- The device must be as generic as possible which means the definition of its interface should reflect the service rather its underlying implementation.
  - ✓ For example, a command named “WriteRead” reflects the communication service of a bus (type: message exchange), while a command named “NI488\_Send” reflects a specific implementation of the supplier.
- Show the general characteristics (attributes and commands) of a common type of equipment that it represents.
  - ☞ For example, a command “On” reflects the action of powering on a PowerSupply while a command named “BruckerPSON” reflects a specific implementation which must be avoided.

# Performances related design recommendations

- Do not make assumptions about the nature of the clients!
  - The behavior of the Device must be the same if I use a client that reads a single attribute or a client that reads them all
- Do not make assumptions on the number of clients connected to a Device
  - At the beginning 1 client is connected
  - But in real operation after a few months or years , you may end with tens of clients on a single device

***Recommendation : The response time of the device should be minimized and in any case lower than the default Tango timeout***

# Recommendations for the specifications/design/development phases

- ❑ During the specification process define the attributes, commands, states of your Device
- ❑ Write test cases focusing on error scenarios
- ❑ Use usual UML diagrams :
  - ☞ To clarify data relationship within the internal device software objects
  - ☞ Use sequence/state diagrams when state transitions are complex
  - ☞ Make a pair code review and cross check with the Recommendations Guidelines



# General Code implementation Consideration

- ❑ Don't forget that the TANGO interface is only a mean to insert a service in a control system.
- ❑ Therefore, it is necessary to think the device internal design like any other application and just add the TANGO as an interface on top of it.
- ❑ As a rule of thumb if the code implemented within the POGO markers is too long, a good practice is to move it to another class.
  - ☞ Then Pogo generated methods will be only a few lines of code long.

## *Recommandations :*

- *In practice, it is necessary to avoid mixing the generated code by POGO and the developer's one.*

# Language

- ❑ The TANGO community is international and the developments could be shared with the community, so it is recommended to use ENGLISH for a device development.

## *Recommendations :*

### *English will be used for:*

- *The interfaces definition (attributes and commands)*
- *The device documentation (online help for command usage and attributes description)*
- *The comments inserted in the code by the developer*
- *The error messages*
- *The name of variables and internal methods added by the developer.*

# Code generation : POGO is mandatory

## *Recommandations :*

- The use of POGO is mandatory for creating or modifying the device interface.*
- Every command, attribute, property or device state must be fully documented; this documentation is done via the POGO tool.*
- The automatically generated code by POGO must not be modified by the developer.*
- The developer must include its own code in the “PROTECTED REGION” specified parts.*

Definition	Properties
Default Attribute Properties	
Label	Temperature
Unit	*C
Standard Unit	
Display Unit	
Display Format	%6.3f
Max. Value	
Min. Value	
Max. Alarm	120
Min. Alarm	-100
Max Warning	
Min Warning	
Delta time	
Delta value	
Description :	Temperature read on a PT100 thermocouple channel

# Tango interface : naming rules

- Having homogeneous conventions for naming attributes, commands and properties is a good way to promote DeviceServers reuse inside the Tango collaboration (or in your institute)

## *Recommandations :*

- *The **Tango class name** is obtained by concatenating the fields that compose it – each field beginning with a capital letter:*
  - *Eg : MyDeviceClass*

# Tango interface : naming rules

## ***The attribute naming recommendations are:***

- ***Name composed of at least two characters***
- ***Only alphanumeric characters are allowed (no underscore, no dashes)***
- ***Start with a lowercase letter***
- ***In case of a composite name, each sub-words must be capitalized (except the first letter)***
- ***Prohibit any use of vague terms (eg: readValue).***

## ***The command naming recommendations are:***

- ***Name composed of at least two characters***
- ***Only alphanumeric characters are allowed (no underscore, no dashes)***
- ***Start with a uppercase letter, In case of a composite name, each sub-words must be capitalized***
- ***Prohibit any use of vague terms (eg: Control).***

# Tango interface : naming rules

- ❑ It is a good practice that a particular signal type is always named in a similar way in various DeviceServers.
  - ☞ For example the intensity of a current should always be name “*intensity*” (and not “*intens*”, “*intensity*”, “*current*”, “*I*” depending on the DeviceServers).
  - ☞ This allow the user to quickly make the link between the software information and the physical sensor and reciprocally.
- ❑ The choice between the *Expert* or the *Operator* level for an interface must be thoughtful.
- ❑ All basic commands must be accessible at the OPERATOR level

# Implementation

## Guidelines



# Tango polling mechanism

- ❑ TANGO implements a mechanism called *polling* which alleviates the problem of equipment response time
  - ☞ (which is usually the weak point in terms of performance).
- ❑ From the perspective of the device activity, the polling is in direct competition with client requests. The client load is therefore competing with polling activity
  - ☞ This means that polling activity has to be tuned in order to keep some device free time to answer client requests.

## ***Recommandations :***

- ***The recommendation for device polling tuning is to keep the device free 40% of time.***

# Tango threading mechanism

- Threading is a possible solution for the load problem
  - ☞ a thread (managed by the device developer) supports communication with the material (polling or other) and the data obtained are put in the “cache”.
  - ☞ You can now produce the “last known value” to the client at any time and optimize the response time..
  - ☞ This approach, however, has a limit where it is necessary to reread the hardware to assure clients that the returned value is the system “current state”.

## ***Recommandations :***

- ***When the design of the Tango class requires threading:***
- ***• in case of simple thread usage, in C++ the recommendation is to use a C++11 thread***
- ***• In case of acquisition thread with messages exchange in C++ the recommendation is to use `Yat4TANGO::DeviceTask` class..***

# Use Yat and Yat4Tango libraries

- YAT library offers many utilities for :
  - ☞ Portability
  - ☞ Threading
  - ☞ Active Objects features
  - ☞ Timers
  - ☞ Date/Time
  - ☞ Etc..
- YAT4Tango offers utilities linked with Tango
  - ☞ logging , exception helpers, etc ..
- Both are :
  - ☞ hosted within the tango-cs repository
  - ☞ actively developed and supported by SOLEIL

***Recommandation :Use Yat and YAT4Tango when portability (Windows /linux) is required or to benefit from advanced features for threading , etc ..***

# Error handling : Use Tango logging system

- ☞ The introduction of logging in the device code enables easy development, bug research and the user
  - ☞ understanding of the device operations
    - ✓ DEBUG\_STREAM : for software developpers
    - ✓ INFO\_STREAM : user info (start/stop of a measurement, a process)
    - ✓ WARN\_STREAM : warning messages (degraded mode ,etc)

***It is not mandatory, but highly recommended to add an attribute named “log” in the device interface, which tracks all the internal activity of the device (as defined in TANGO Logging).***

# Exception handling

- ❑ The developer has to ensure:
  - ☞ That any exception is caught, completed (TANGO allows it) and spread (use of the `rethrow_exception` method),
  - ☞ If an error occur it must be logged using the Tango Logging Service
  - ☞ That the return code of a function is always analyzed,
  - ☞ That the device Status is always coherent with the State,
  - ☞ That the error messages are understandable for the final user
- ❑ The Status is the indicator that will help the user to find the error reason.
- ❑ But do not throw exception in the `init_device` method !! (the device must be kept alive in all cases)
- ❑ Of course , imagine all errors scenarios (cabling problem with the equipment, ..)

# Exception handling

- It is a good practice to standardise the Reason Field of the Tango exception

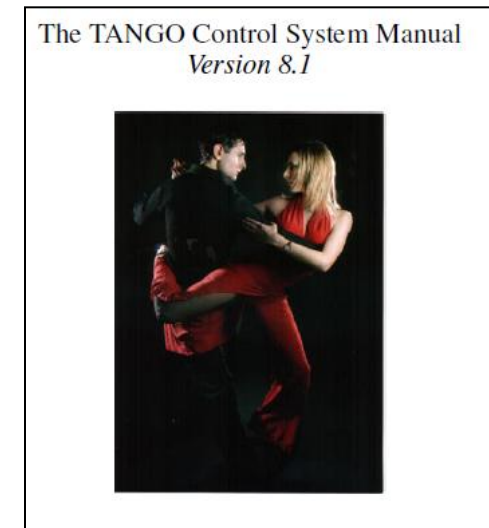
Nom standardisé pour les types d'erreur
OUT_OF_MEMORY
HARDWARE_FAILURE
SOFTWARE_FAILURE
HDB_FAILURE
DATA_OUT_OF_RANGE
COMMUNICATION_BROKEN
OPERATION_NOT_ALLOWED
DRIVER_FAILURE
UNKNOW_ERROR
CORBA_TIMEOUT
TANGO_CONNECTION_FAILED
TANGO_COMMUNICATION_ERROR
TANGO_WRONG_NAME_SYNTAX_ERROR
TANGO_NON_DB_DEVICE_ERROR
TANGO_WRONG_DATA_ERROR
TANGO_NON_SUPPORTED_FEATURE_ERROR
TANGO_ASYNC_CALL_ERROR
TANGO_ASYNC_REPLY_NOT_ARRIVED_ERROR
TANGO_EVENT_ERROR
TANGO_DEVICE_ERROR
CONFIGURATION_ERROR
DEPENDENCY_ERROR
NO_DEPENDENCY

# Resources available to work within the Tango community



# Documentation

- ❑ The Tango reference manual is the best entry point !!
  - ☞ Please RTFM (“Read this Fucking Manual”)
- ❑ There are tutorials on the “Tango www site”
- ❑ A document “Tango DeviceServers design consideration”
  - ☞ Tries to summarize all the question you must think about before coding
  - ☞ This document tries to summary years of mistakes and unanswered questions on the “How To” develop “good” Tango



SOLEIL NEXEYA  
SYNCHROTRON SYSTEMS

Version 1.4

TANGO DeviceServers  
Design & Implementation Guidelines

Diffusion :

Distribution list : Tango mailing list  
Copy to :

Date	Writer	Reviewer	Approver	Modifications	Version
19/06/2012	S.GARA S.MENOLLI	N.LECLERCQ A.BUTEAU			0
11/09/2012	MIRJAM LINDBERG	N.LECLERCQ A.BUTEAU			1
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16/11/2012	JM.CHAIZE E.TAUREL	A.BUTEAU		Remarks following SOLEIL/ESRF meeting	3

# Community tools

- ❑ The Tango “Pink” site is the central place to find documentations, examples, etc ..
  - ☞ It is unfortunately managed on a “best effort” basis and it may be sometimes outdated
  - ☞ Moreover the navigation on this Web site is sometimes strange : Use Google !!
- ❑ The mailing list (tango@esrf.fr) is the best way to have fast responses to technical problems
  - ☞ It is an active mailing list (a few hundreds of post per year)
  - ☞ And the spirit is quite professional and avoid the (usual ?) religious war on software language
  - ☞ So feel free to post . Tango dancers are proud of Tango and usually help
- ❑ The Tango meetings
  - ☞ Are important because you physically meet the Tango dancers
  - ☞ They last 1,5 days and the program is usually the following
    - ✓ Status on each institute Tango activity , resources, projects ,etc .
    - 03/18/2013 ✓ Status on Tango work packages
    - ✓ New technical ideas or projects

# Source Code Management

# Release policy and download site

## ❑ Tango Core

- ☞ There is a major release each 18 months
- ☞ The technical roadmap were defined by the E.C following the proposal of the Collaboration Coordinator
- ☞ This major release is downloadable on the official Tango site
  - ✓ and integrates new versions of most the workpackage new releases

## ❑ Other Tango workpackages

- ☞ Have their own lifecycle mostly driven by the institute in charge requirements constraints
- ☞ For exemple the “Tango Archiving system” is released 5 times per year
  - ✓ Because a new version is deployed on the SOLEIL accelerator 5 times per year
- ☞ They should be (in theory) accessible through the official Tango site

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✓ Or on SOLEIL Maven repository

✓ Or on E S RF http

- ❑ For each software module an SVN structure has been defined
  - ☞ in trunks, tags, branches “directories”
- ❑ The tango-cs <http://sourceforge.net/projects/tango-cs>
  - ✓ hosts Tango Core system and the workpackages defined previously
  - ✓ Write access is granted only to Tango projects contributor
  - ✓ Repository organization mimics Tango workpackages organization
- ❑ Tango-ds (<http://sourceforge.net/projects/tango-ds/>) hosts Tango DeviceServers which may be of common interest
  - ☞ because they do not rely on particular memory mapping or specific electronics
  - ☞ Most of them control commercial instruments
    - ✓ Ex : motor controllers, Agilent instruments, ADC boards, etc ..
  - ☞ Or generic software processes or calculations
    - 03/18/2018 ✓ Data fitting, image analysis, etc ..

# Tango-ds repository organization

- AcceleratorComponents
- Acquisition
- BeamDiagnostics
- BeamlineComponents
- Calculation
- Communication
- CounterTimer
- InputOutput
- MagneticDevices
- MeasureInstruments
- Motion

- OtherInstruments
- PowerSupply
- RadioProtection
- SampleEnvironment
- Security
- Simulators
- SoftwareSystem
- StandardInterfaces
- Temperature
- Training
- Vacuum

List is available :

<http://www.tango-controls.org/device-servers>

- ❑ There are hundreds of Tango DeviceServers stored there
- ❑ With a large variability in terms of quality and reusability
- ❑ Nevertheless please store your project on this repository if it may be reused elsewhere
  - ☞ i.e not directly linked to a specific hardware
  - ☞ Interface a commercial instrument
  - ☞ Or a generic “software” component



# Conclusion

- ❑ Tango is a very intuitive system from the user point of view
- ❑ It is also easy to understand for software developers
- ❑ Nevertheless , to get high quality results , software engineering methods are mandatory at all phases (specifications, design, implementation, code management,etc.)
- ❑ Entry cost in the Tango community decreases in the last years because of :
  - ☞ Documentation efforts (Tango Book and Guidelines)
  - ☞ Community Help
  - ☞ Development of the eco system of applications, libraries , development tools (POGO), code repositories, etc..
- ❑ But you still have to learn and make efforts

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