#### MAX IV Laboratory Status

#### Kontrollsystem & IT Services (KITS) Tango Workshop, ALBA, 23rd May 2013



## Kontrolls & IT Services (KITS)

We are a small group

- Controls Software
  - Vincent Hardion,
  - Andreas Persson,
  - Mirjam Lindberg,
  - Antonio Milan
  - (+2 recruitments)
- Controls Hardware
  - Julio Lidon-Simon,
  - Jerzy Jamroz
  - (+2)
- Networks, Servers, Systems
  - Tobias Lundquist,
  - Daniel Liikamaa (+2)
- \_IT Support
  - Tor Auster, Andras Vancsa,
- \_ Strategy, Scientific & Information Management Systems
  - Krister Larsson, Jason Brudvik (+1)
- Currently agreed total group size of 19 for MAX IV
  - \_ Based on initial facility with 7 beam lines



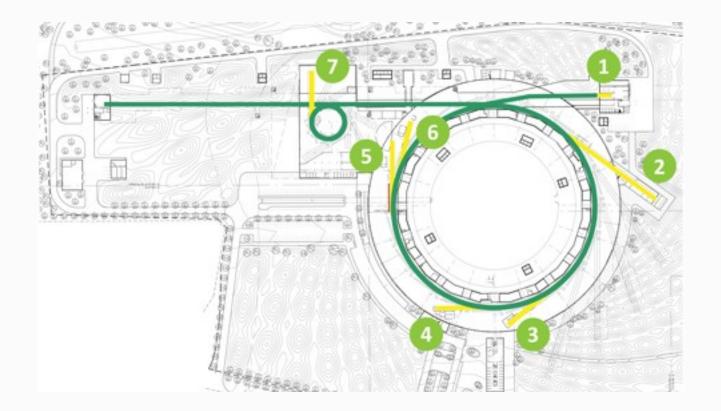


## MAX IV Design Features

- Full energy linac
  - Free Electron Laser planned later in 2018 onwards
- Short pulse facility at end of linac
   Femtosecond time resolved experiments
- Two storage rings (1.5GeV and 3GeV)
   Favoring the large soft X-ray community
- Integrated multibend acromat magnets

   Part of reducing accelerator component scale

### MAX IV Topology





## 8 Beam Lines

- Vinue och Alice
   Image: Construct of Alice

   Vallenbergs
   Image: Construct of Alice

   Vallenbergs
   Image: Construct of Alice

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   Image: Construct of Alice
- BioMAX Protein Crystallography
- VERITAS Resonant Inelastic X-ray scattering
- HIPPIE High Pressure High Resolution Electron Spectroscopy
- NanoMAX micro and nano beams for imaging, diffraction scattering, fluorescence
- FemtoMAX femtosecond experiments
- ARPES (1.5GeV) angle-resolved photoelectron spectroscopy
- BALDER hard X-ray absorption spectroscopy
- FinEstBeams (1.5GeV) Finnish Estonian materials science





## MAX IV Main Milestones

- Linac installation access mid-May 2013
  - Mobile phone coverage and fibre connection being installed.
- Linac commissioning start March 2014
- Femtomax (SPF) end of 2014.
- Storage rings commissioning March 2015
- MAX IV open 21st June 2016









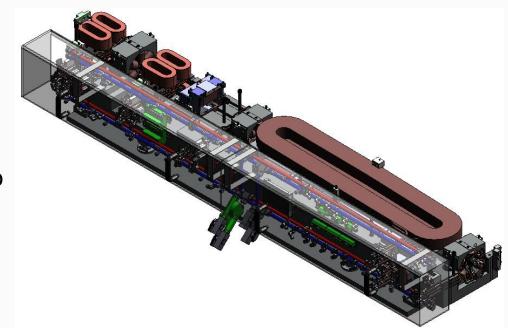
#### MAX IV Accelerator Sub-systems

- Power supplies
- Timing
- RF
- vacuum, safety, magnets, machine protection, cooling, diagnostic, waveguides, laser, accelerator units, LLRF....



## **Magnet Power Supplies**

- Specification for 1008 magnet power supplies
- Ranges from 10W to 234kW, 16-18bit
- Chose 'PolyAmp' (Delta), 'Danfysik' and 'Itest'.
  - We are writing the Tango devices
- Coils for fast orbit correction may be installed?

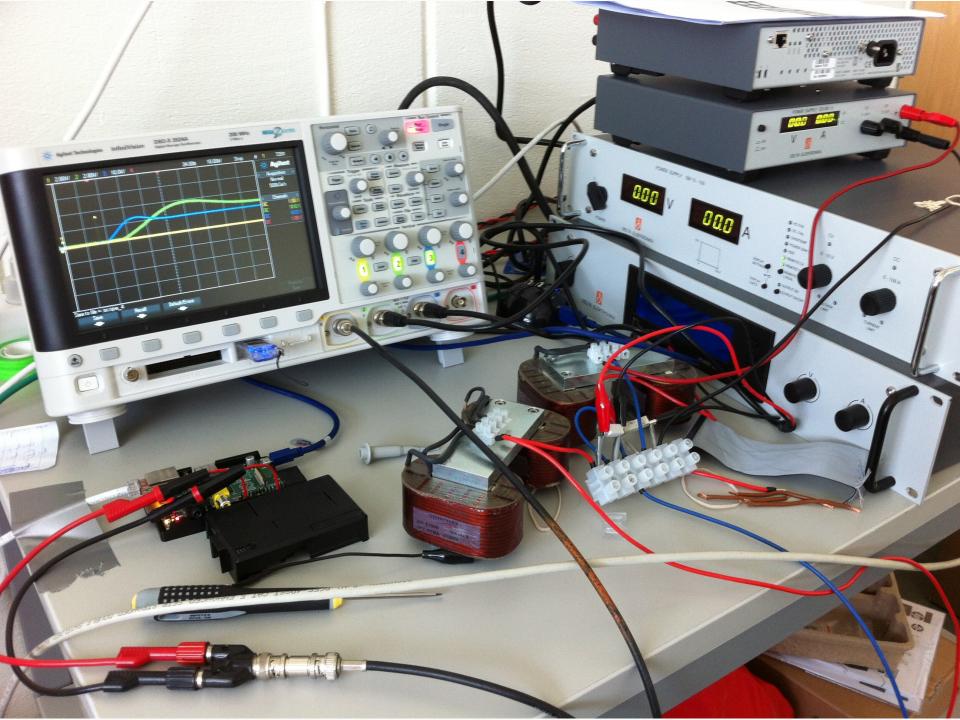




## **Power Supplies**

- Site Acceptance Tests (|Itest, Delta Elektronika and Danfyisk)
  - \_ No tango testing itself
  - \_ Itest (c++ library delivered)
  - \_ Delta elektronika (library developed with similar interface)
  - \_ Attempt to converge towards standard interface later
  - \_ Stress testing and performance/response time testing (using scopes)
  - \_ Danfysik yet to come
- Results
  - \_ Itest passed all the tests
  - Delta elektronika has 3 or 4 different interface models, less functional than itest (triggers)





# Timing System

 Original design based on trigger boxes from Berkley Nucleonics (BNC)

– Only linac RF and injection into storage rings considered

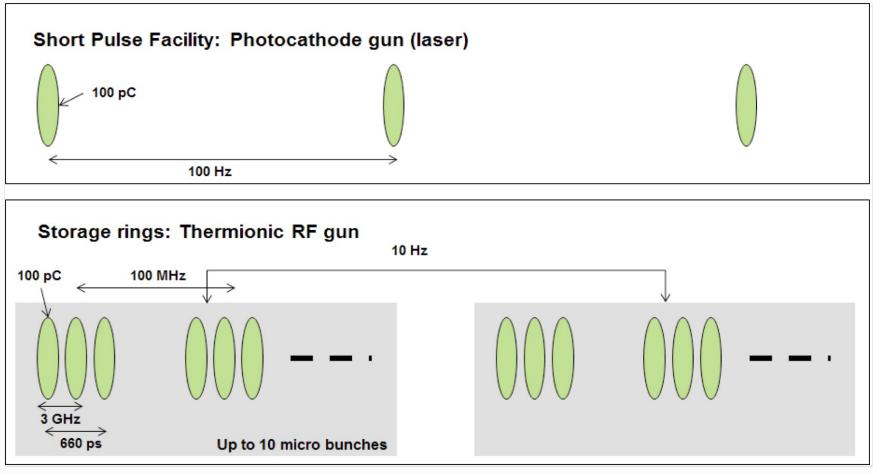
• New design proposed by Julio and Jerzy

– Takes into account femtomax and future SPF

- Also covers future needs of storage rings and special mode
- Uses MRF system in combination with DG645 boxes in original design
- \_ Inspired after visit to XPP (pump probe) beam line at SLAC
- Cost low due to using EVGs from libera brilliance



### **Bunch structures**





## **Motion Controllers**

- Max IV chose IcePAP
  - Currently loaning 30 racks from ESRF
    - Linac, femtomax beam line
  - Starting procurement of 50 racks
    - Storage rings and future beam lines
- Control with Sardana and Tango device server







# Ongoing Projects with Tango

- MAX IV Injection Test Gun
- EPU 61 undulator (SPECIES beam line)
- Magnets Power supplies



## MAX IV Test Gun

- Both Thermionic and Cathode Guns needed
  - \_ photocathode Gun for SPF (injection at 100Hz)
  - \_ Thermionic laser gun needed for storage rings injection (10 Hz)
- Commissioning happening with MAX III
  - \_ Controlled from original MAX control room
- Controls Perspective... using Taurus interface to
  - \_ Plc interface to power supplies (RSView via OPC)
  - \_ Vacuum controller (gamma vacuum SPCe small pump controller)
  - \_ Eurotherm via ModBus PyPLC from ALBA
  - \_ Temperature control circulator (phoenix2) via serial port
  - \_ Cameras (LIMA)
  - \_ Motorised screens to Trinamic motor



## Test Gun & LIMA

- LIMA integration
  - Linac beam viewers point grey gigE cameras plugin implemented
    - Teething troubles to get first production server in use.
      - Changing modes etc, cause blocking of communication
      - Configuration of the camera buffering to get best results
    - Learning to fit the camera behaviour into the LIMA model
  - Using Tango 8 events to get image stream from server to client
    - Economises some network bandwidth
    - Seems reliable







# EPU 61 Undulator

- No in house experience, therefore use framework contract and hire CosyLab
  - 3-4 visits
    - Setting requirements
    - Development with real hardware
    - Testing and Site acceptance (>30 documented test cases)
- EPU 61 was installed on i511 on schedule with no problems
  - Scientists happy, disturbance compared to old undulator the same but with no correction coils





## SPECIES on MAX II

- MAX IV standards on existing MAX II beam line
  - Our opportunity to test our MAX IV strategy
  - But an extra project not planned!



### Thankyou..

#### Questions?

