# **Tango Integration of Modern 2D Detectors**

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## **Outline**

- > Background
- > Challenges
- > Hardware
- > Software implementation
  - Architecture
  - Software core
  - Detector Module
  - Tango integration
- > Summary and Outlook



# **Background**

- Motivation
  - Provide detector with high sensitivity, high resolution, high frame rate and large area
- > New detector development
  - LAMBDA 2D detector
  - Developed by DESY.
  - Based on the Medipix3 readout chip
  - Single Module:1536 x 512 pixels
  - Support both 12 and 24 bit image modes
  - Maximum frame rate:2000 frames/second with 12 bit mode

Large Area Medipix Based Detector Array
(LAMBDA)

Other detectors (e.g. AGIPD) are under development as well



# **Challenges**

- > Large amounts of data from LAMBDA
  - Data transmission via UDP protocol
  - Each raw image: ~1.2 MBytes
  - With maximum frame rate: 2.4 GBytes/s
  - How do we receive reliably such amounts of data?
- > Multiple modules compatibility
  - LAMBDA: full size module (1536 x 512 Pixels) half size module (768 x 512 Pixels) three modules system
  - Other high speed detector (e.g. AGIPD) with same data transmission protocol
  - How do we generalize the software and make it reusable?

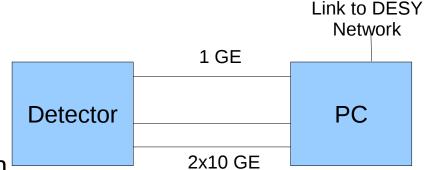


### Hardware

- > Detector PC
  - Dell PowerEdge R620 Server
  - Intel(R) Xeon(R) CPU E5-2667 0 @ 2.90GHz X 12 cores
  - RAM: 256 GBytes
  - Hard disk: 4 TBytes
  - 6 X 10 GE NICs
  - 2 X 1 GE NICs



- > LAMBDA system Overview
  - 1 GE TCP link, slow control
  - 10 GE UDP link, data transmission

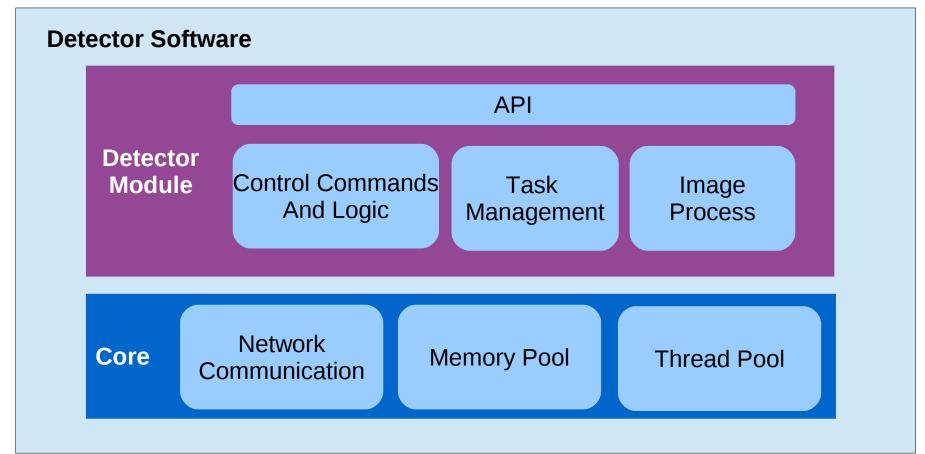




### **Software Architecure**

#### > Architecture

Divided into core and module dependent parts



### **Software Core**

#### > Network communication

- Based on Linux socket API
- Data receiving and sending methods are implemented

### > Memory pool

- Based on boost fast pool allocator
- Support different data types by using generic programming technology
- FIFO circular buffer without overwriting

### > Thread pool

- Based on boost thread implementation
- Used to support variable tasks (e.g. data receiving, image decoding)



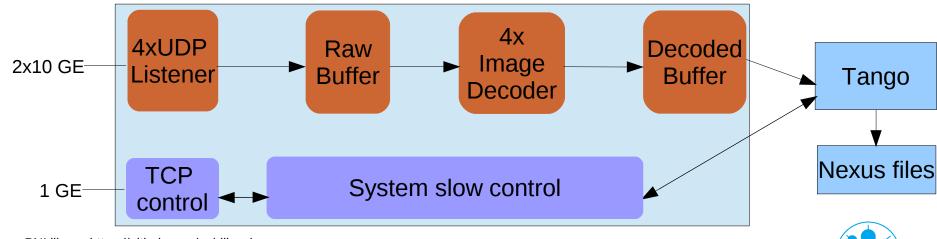
### **Detector Module**

- > Module dependent control
  - Detector control commands are implemented (e.g. setting shutter time)
  - Basic control logics are implemented (e.g. start acquisition)
- > Task management
  - Create tasks for parallel computing (e.g. UDP listener, image decoding)
  - Created tasks are pushed to thread pool
- > Image process
  - Provide image process related method (e.g. decoding image, distortion correction)
- > API for further integration
  - Interface for developing user applications (e.g. tango server)



# **Tango Integration**

- > Tango server implementation
  - Based on the interface of detector software, tango attributes are created
  - Based on PNI library, data are saved to local disk with Nexus format
- > LAMBDA system workflow
  - 4 x UDP listeners;4 x Image Decoders
  - Parallel running: UDP receiving data, image decoding, saving data to disk
  - Maximum images to take: 150,000 images (75 seconds)



# **Summary and Outlook**

- > Successfully integrated into tango control system at PETRA3 in DESY
- > Works reliably with high speed(2000 fps) data acquisition mode
- > Bottleneck on data compression, local file saving slowly
- > The core part of the software is reused in AGIPD
- > With this software, integration to LIMA is possible
- > Increase compression speed with parallel running HDF5 external filter
- > In future, with help of the GPFS file system from IBM. The data will be saved to DESY central storage rather than local disk
- Three module LAMBDA system is being developed and will be integrated into tango



# Thank you

